

THE DATUM UNIVERSAL TRANSDUCER INTERFACE

The Datum Universal Transducer Interface has been designed to accept signal from all of the Datum Electronics range of Rotary and Static Torque Sensors.

The sensor ranges supported include:

M425 Rotary Torque Transducers

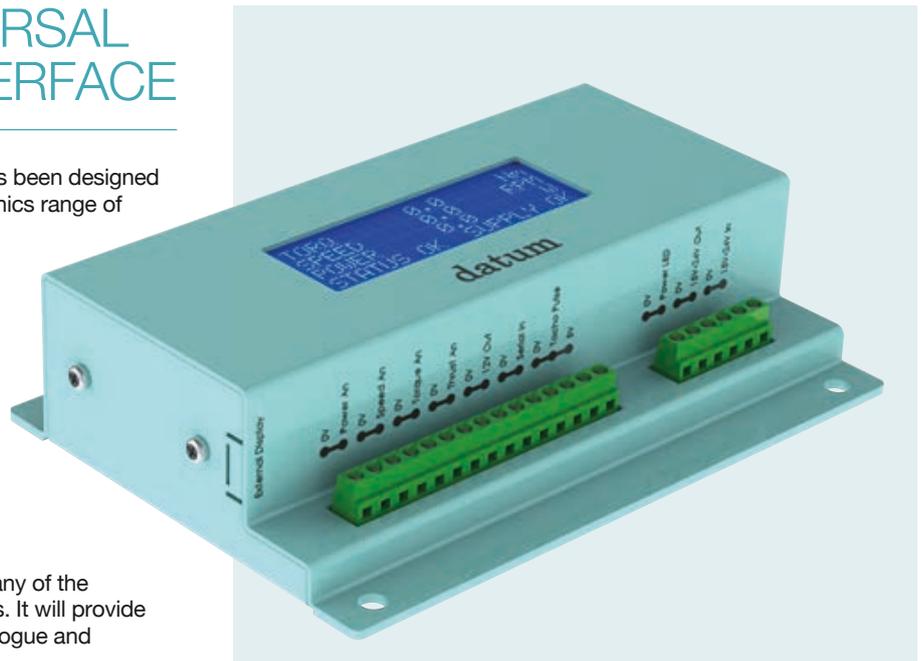
RS/FF425 Rotary Torque Transducers

SPS Marine and Heavy Industrial Torsionmeter Systems

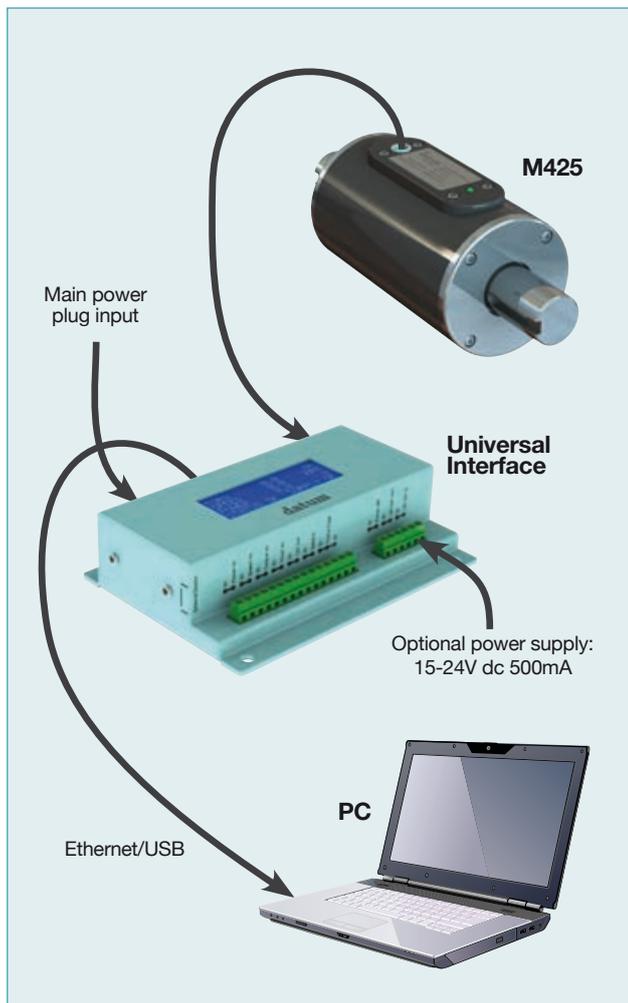
NTM Naval Marine Torsionmeter Systems

RS/FF410 Static Torque Transducers

The interface will accept the serial data from any of the above and most of the earlier Datum products. It will provide a display of the data and a wide range of analogue and serial data outputs.



TYPICAL CONFIGURATION



OUTPUTS PROVIDED

Output power - for the M425, RS/FF425, RS/FF410 and the SPS Marine System

Ethernet - data output and main configuration interface

Mini USB Type B - data output and configuration interface

USB Type A - logging to memory stick

RS485/RS232 Serial - data output

4 channels of analogue - user configurable to 4-20mA, 4-12mA, +/-5Vdc, +/-10Vdc, 0-5Vdc and 0-10Vdc

The data used for these outputs can be user selected from the Torque, RPM and Power data plus an additional strain input (often used for shaft bending or thrust).

Additional Input

The Datum Universal Transducer Interface will also accept an input from an external shaft speed tacho.

Power Supply 15-24Vdc.

UNIVERSAL INTERFACE CONNECTIONS GUIDE

Front

Back

<ul style="list-style-type: none"> Power Analogue (2 way) Speed Analogue (2 way) Torque Analogue (2 way) Thrust Analogue (2 way) *12 Volts OUT (2 way) *Serial IN copy (2 way) Tacho Pulse IN (3 way) Power LED (2 way) 15V - 24V OUT (2 way) **15V - 24V Power IN (2 way) 	<ul style="list-style-type: none"> Serial Torque Sensor Factory Reset Zero Reset Ethernet USB Type A - Data Logging USB Mini B - Primary USB to PC Interface Main Power Input Serial Output
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*The **12V Output** and the **Serial IN Copy** are screw terminals that duplicate the connections for the serial torque sensor 'D' connector.

**Alternative power input terminal.

GRAPHIC USER INTERFACE

Datum data logging software

The Datum data logging and configuration software provides a wide range of control functions of the M425 including set-up and configuration options plus data logging.



Channel	Input	Output	Zero	Full Scale	Units	Error Condition
Channel 1	Force	4-20mA	0	5000	Nm	
Channel 2	RPM	4-20mA	0	1000	RPM	
Channel 3	Power	4-20mA	0	5000	W	
Channel 4	Temperature	4-20mA	0	5000	°C	

Select Transducer Type: Series 425

Series 425 Options:

- Torque: 25.41
- RPM: 25.41
- Power: 25.41
- Thrust: 25.41

SPM Options:

- Temperature: 25.41
- Shaft Voltage: 25.41

C440 Options:

- Rotations: 25.41
- Angle: 25.41
- X-Axis: 25.41
- Y-Axis: 25.41
- Z-Axis: 25.41

SPECIFICATIONS

SIGNAL INTERFACE OUTPUTS

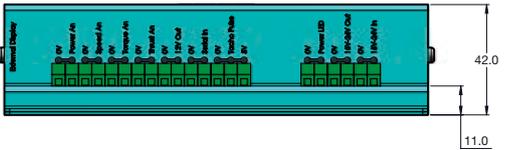
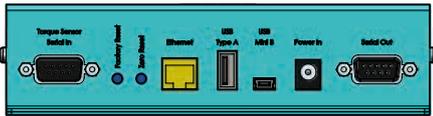
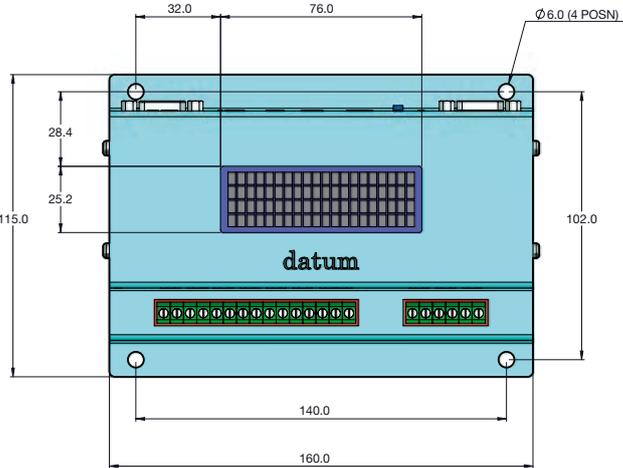
Digital:	
RS485	Serial data
RS232	Serial data
Ethernet	Data and configuration
MODBUS UDP	Serial data
USB Type Mini B	Serial data
USB Type A	Data logging

Analogue:	
All four of the M425 Transducer's analogue output channels can be configured for any of the following settings by the user: 4-20mA configured 4-20mA (4-12-20mA); +/-10Vdc, +/-5Vdc, 0-10Vdc or 0-5Vdc	
A typical configuration arrangement would be as follows:	
Channel 1 - Torque	from 0-500Nm as 4-20mA
Channel 2 - Speed RPM	from 0-100-rpm as 0-5Vdc
Channel 3 - Power	from 0-5000W as 4-20mA
Channel 4 - Spare	

Display:			
Torque	Speed RPM	Power	Status

ENVIRONMENT

Normal Specification Range	10 to 60°C
Operating Range	-10 to +70°C
Storage Range	-35 to +75°C
Environmental Protection	IP54 (see RS425 for IP67/68)
Electromagnetic Compatibility	EN61326-1:2006 (IEC61000-4), IEC60945)



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